Measurement of Potential Drop Distribution by Scanning the Closely Coupled Probes Sensor for Sensitive NDE of Shallow Surface Cracks

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Highly sensitive nondestructive evaluation of shallow surface cracks is realized through the distributions of d-c potential drop obtained by scanning the closely coupled four-point-probes sensor around the crack. A methodology is developed for evaluating the depth and length of a three-dimensional surface crack from the potential drop profiles measured across and along the crack, where the experimental result is compared with the corresponding prediction of finite element analysis. The highly sensitive characteristic of the measured profiles is also extended to the quantitative NDE of cracks. Usually, the potential drop techniques use four probes: a set of two probes for current input and output, and another set of two probes for measuring the potential drop. In some special cases, the current induction and also the measurement of potential drop have been performed in a non-contacting manner by utilizing the electromagnetic phenomena. In the case of usual method of evaluation, the potential drop is measured near the crack, and the current input and output probes are located at a large distance from the crack to make a uniform current flow in the region far from the crack; see the work of Johnson as a typical example.6)

The closely coupled probes potential drop (CCPPD) technique using four probes, which are in close proximity to each other, has been proposed by Saka et al.7) to enhance the sensitivity of d-c potential drop technique. The technique measures the surface potential drop between the two measuring probes, where the objective crack is located at the center of the four probes, and has been successful for quantitative NDE of smaller 3-D fatigue cracks using a calibration equation derived by the finite element (FE) analysis.8) Recently, the industrial demand of developing highly sensitive NDE technique, which is capable of accurately characterizing sub-millimeter cracks on the surface of structural components, is realized to be quite strong, especially for the early detection of small defects and their quantitative evaluation enable us to remove such small cracks or to repair them in optimum way thereby providing significant economic, reliability, and safety benefits.

The present paper describes a scanning approach of d-c potential drop method of testing for realizing sensitive detection as well as precise evaluation of shallow surface cracks in metallic structures. The measurement of potential drop distribution around a crack is performed by scanning the CCPPD sensor, in which both the current supplying and measuring probes are in close proximity to each other. The potential drop profiles across the cracks having various depths and lengths are first obtained by FE method, and then analyzed to develop a suitable methodology for accurately evaluating the depth and length of surface cracks from the potential drop profiles measured across and along the crack. It is found that the method is capable of enhancing the sensitivity to a great extent, especially for the sub-millimeter shallow surface cracks, which, in turn, ensures accurate quantitative characterization of the cracks. The reliability as well as superiority of the present evaluation technique is verified by conducting experiments on simulated 2-D cracks and also on 3-D sub-millimeter fatigue crack together with the potential drop image of the cracked surface.

1. Introduction

Nondestructive evaluation (NDE) of cracks is needed for integrity assessment of structures based on fracture mechanics, and many techniques, for example, the ultrasonic techniques,1–3 the eddy current techniques,4,5 the electric potential drop techniques,4,6–12 etc., have been reported for NDE of cracks. The electric potential drop techniques are basically classified into two categories—direct current method6–9 and alternating current method,4,10–12 and have been widely used for materials evaluation as well as the quantitative NDE of cracks. Usually, the potential drop techniques use four probes: a set of two probes for current input and output, and another set of two probes for measuring the potential drop. In some special cases, the current inductive10,12 and also the measurement of potential drop10) are performed in a non-contacting manner by utilizing the electromagnetic phenomena. In the case of usual method of evaluation, the potential drop is measured near the crack, and the current input and output probes are located at a large distance from the crack to make a uniform current flow in the region far from the crack; see the work of Johnson as a typical example.6)

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2. Procedure for Numerical Analysis

The problem of current flow in a material is governed by the Laplace equation, which is given by,

$$\nabla^2 \phi = 0, \quad (1)$$

where \(\phi\) is the electrical potential and \(\nabla^2\) is the 3-D Laplace operator. The Laplace equation can be solved by FE analysis, and \(\phi\) is numerically determined. The region concerned was discretized with the 8-noded isoparametric 3-D solid elements. Very fine meshes are used around the region of the crack as well as around the scanning region; the minimum pitch used for the present discretization was 0.05 mm. Consider the problems of measuring the potential drops at the surface of the cracked block by the conventional potential

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The depth of the crack, \( b \), along the surface of the crack, and this value of potential drop, \( V \), at which the current flow probes flow through the sensor is located at the position \((0,0)\) for evaluating the crack depth. The precise measurements of the potential drops at the points B, C, D and E may be difficult because these are obtained at the positions where a potential drop measuring probe or a current probe is very close to the crack. On the other hand, the profile of the usual technique with uniform current flow has only three peaks A, B and C, which are shown as inset within the graph of Fig. 2. The technique, both the potential drop measuring probes and the current probes were moved along the \( x \)-direction on the measuring surface.

In order to establish the methodology for evaluating the real cracks by the CCPPD technique, the 3-D cracks having various values of crack length, \( 2a \), and crack depth, \( b \), were considered, and the corresponding potential drop distributions around the 3-D cracks were obtained by the 3-D FE analysis.

### 3. Results of Numerical Analysis

#### 3.1 Potential drop profiles across the surface crack

The potential drop profiles along the \( x \)-direction, \( V(x,0) - V_0 \), for both the cases of the CCPPD technique and the conventional potential drop technique with uniform current flow are shown in Fig. 2. As appears from the figure, the profiles of both the potential drop techniques are symmetric about the center of the crack \((x = 0)\). The potential drops corresponding to five different sensor positions with respect to the crack, denoted by the points, A, B, C, D and E, as shown in Fig. 2, are identified in the profile obtained by scanning the CCPPD sensor and the corresponding positions of the current and measuring probes are schematically illustrated in the same figure. The point A is obtained when the sensor is located at the position \((0,0)\), at which the current and potential drop measuring probes are symmetric to the crack, and this value of potential drop, \( V(0,0) \), can be used for evaluating the crack depth. The precise measurements of the potential drops at the points B, C, D and E may be difficult because these are obtained at the positions where a potential drop measuring probe or a current probe is very close to the crack. On the other hand, the profile of the usual technique with uniform current flow has only three peaks A', B' and C', which are shown as inset within the graph of Fig. 2.

**Fig. 1** Schematic of the potential drop technique with uniform current flow (a) and the CCPPD technique (b).

**Fig. 2** The potential drop profiles along the \( x \)-direction, \( V(x,0) - V_0 \), for both the cases of the CCPPD technique and the potential drop technique with uniform current flow for 2-D crack \((b = 2\, \text{mm})\).
value of $V(0, 0)$ at the point $A'$ may be used for determining the crack depth, but the associated magnitude of $V(0, 0)$ is very small than that at point A obtained by the CCPDPD technique. The above comparison reveals that the CCPDPD technique is more suitable for the evaluation of cracks than the uniform current flow technique, and it enables us to realize the sensitive NDE of small cracks. Furthermore, the potential drops observed between the points C and D of the CCPDPD profile have the possibility to be used for NDE of small cracks, because, in this region, neither the potential drop measuring probes nor the current probes are located very close to the crack, and thus the corresponding potential drops can be stably obtained. In this paper, the potential drop, $V(0, 0)$, at the point A obtained by the CCPDPD technique is denoted by $V_1$, and that obtained at a probe position between the points C and D, $V(2.5, 0)$, is denoted by $V_2$. It is noted that in the earlier studies, only the values of $V_1$ and $V_0$ were used for the evaluation of crack depths.\(^{7,8}\) As observed from the potential drop profile across the crack, $V_2$ is more attractive for the evaluation of small cracks, because the difference in the potential drop, $V_0 - V_2$ is much larger than that of $V_1 - V_0$. Note that no such stable potential drop $V_2$ is appeared in the potential drop profile obtained by the conventional technique with uniform current flow.

In an attempt to explain the reason why $V_2$ takes a lower value than $V_0$, let us consider the 2-D problem of measuring the potential drop, $V_2$, on the surface of a cracked material by the CCPDPD sensor, where the crack is located between the current output and a potential drop measuring probe, as shown in Fig. 3(a). The electric crack problem can be divided into two sub-problems as shown in Figs. 3(b) and (c). For the problem of Fig. 3(b), the same constant current as Fig. 3(a) is applied to the un-cracked material and the potential drop $V_0 (= \phi_1 - \phi_2)$ is obtained at the corresponding positions of the virtual crack, where $\phi_1$ and $\phi_2$ are the surface potentials of the current input and output sides, respectively ($\phi_1 > \phi_2$). Next, the problem of Fig. 3(c) is treated. The same amount of current density as that obtained from the problem of Fig. 3(b) is passed in the opposite direction from the crack surface, and the potential drop $V' (= \phi_4 - \phi_3)$ is obtained, where the surface potentials at the right and left potential drop measuring probes are denoted by $\phi_1$ and $\phi_2$ ($\phi_4 > \phi_3$). The potential drop observed in Fig. 3(a), is given by

\[
V_2 = (\phi_1 + \phi_3) - (\phi_2 + \phi_4) = (\phi_1 - \phi_2) - (\phi_4 - \phi_3) = V_0 - V' < V_0.
\]

In this way, it is found that $V_2 < V_0$. It is thus realized from eq. (2) that the potential drop obtained for the position of the sensor, for which the crack is located in between a current and a potential drop measuring probes, always takes a lower value than that of a crack free position.

### 3.2 Methodology for evaluating 3-D cracks

In this section, the 3-D cracks having $w$ of 0 are considered on the surface of the tested block. The differences of the potential drops for the 3-D cracks of $2a = 20$ mm, $V_1 - V_0$, $V_0 - V_2$ and $V_1 - V_2$, are shown in Fig. 4 as a function of $b$. The values of $V_0 - V_2$ are larger than those of $V_1 - V_0$ for the range of $b$ shown in Fig. 4. The slope $\partial(V_0 - V_2)/\partial b$ is larger than the slope $\partial(V_1 - V_0)/\partial b$ up to the range of $b < 1$ mm. This means that more accurate and reliable evaluation of $b$ can be performed by using $V_2$ compared to that of $V_1$. On the other hand, the slope $\partial(V_2 - V_0)/\partial b$ becomes smaller than the slope $\partial(V_1 - V_0)/\partial b$ for the cracks of $b > 1$ mm. However, the slope $\partial(V_1 - V_0)/\partial b$ shows an increasing characteristic with respect to $b$ for the entire range of interest. Therefore, the value of $V_1 - V_2$ promises the sensitive detection and also the accurate evaluation of $b$ for a wide range of interest.

The differences of the potential drops for the 3-D cracks of $b = 0.5$ mm, $V_1 - V_0$, $V_0 - V_2$ and $V_1 - V_2$, are shown in Fig. 5 as a function of $2a$. The values of $V_0 - V_2$ and $V_1 - V_2$ are quite larger than that of $V_1 - V_0$ for the range of $2a$ shown in Fig. 5. The values of $V_1 - V_0$, $V_0 - V_2$ and $V_1 - V_2$ are found to be affected by the crack length in the range of $2a < 3$ mm. On the other hand, for the range of $2a > 3$ mm, the values of $V_1 - V_0$, $V_0 - V_2$ and $V_1 - V_2$ are almost independent of $2a$. This fact indicates that the measurements of both $b$ and $2a$ would be possible for very short cracks, i.e., the cracks of $2a$ less than 3 mm in the case of $b = 0.5$ mm, by using the value of $V_0 - V_2$ and that of $V_1 - V_2$. On the other hand, the values of $2a$ for long cracks, i.e., for example, the cracks having $2a > 3$ mm for $b = 0.5$ mm, should be determined from the potential drop distributions along the crack, i.e., y-axis.

The differences in the potential drops along the y-axis, $V(0, y) - V_0$ and $V(2.5, y) - V_0$, for the 3-D crack having $2a = 20$ mm and $b = 0.5$ mm are shown in Fig. 6(a), and
those for the 3-D crack having \( 2a = 20 \text{ mm} \) and \( b = 2 \text{ mm} \) are shown in Fig. 6(b). In both the cases of Figs. 6(a) and (b), the crack tip was located at \( y = 10 \text{ mm} \), and at the crack tip, the values of \( V(0, 10) - V_0 \) and \( V(2.5, 10) - V_0 \) are positive and negative, respectively. Here, let us introduce a parameter \( \xi \) defined as follows:

\[
\xi = \frac{V(0, y) - V(2.5, y)}{V_1 - V_2}.
\]

Figures 6(c) and (d) show the variations of \( \xi \) along the crack length for the potential drop profiles shown in Figs. 6(a) and (b), respectively. Now if we set a value \( \xi = 0.1 \), the values of \( a \) in the cases of \( b = 0.5 \) and \( 2 \text{ mm} \) are determined as 9.6 and 10.1 mm from Figs. 6(c) and (d), respectively. The accuracy of this methodology for evaluating \( 2a \) was 4% for the case of \( b = 0.5 \text{ mm} \), and 1% for the case of \( b = 2 \text{ mm} \), which shows good agreement with the actual value of \( 2a \). If a calibration equation of the difference in the potential drop, preferably in terms of \( V_1 - V_2 \), is derived by the FE analysis as a function of \( b \) and \( 2a \), the value of \( b \) can readily be obtained from the equation provided that the value of \( 2a \) is known in advance.

4. Experimental Verification

4.1 Experimental procedure

Two types of cracks, namely, 2-D simulated cracks and 3-D fatigue crack were introduced into the specimens that were machined from austenitic stainless steel, AISI304. Two 2-D cracks were introduced into the plate specimens by electrical discharge machining (EDM); the dimensions of the plate specimens were 250 mm (length) \( \times \) 35 mm (width) \( \times \) 30 mm (thickness), as shown in Fig. 1(a). The values of \( b \) of the 2-D cracks were 0.5 and 2.0 mm, respectively, and \( w \) was 0.1 mm. Figure 7 shows the initial shape and dimensions of the notched sample used to introduce the 3-D fatigue crack. The fatigue crack was developed from the tip of the starter notch [30 mm (length), 3 mm (depth) and 0.5 mm (width)], which was introduced by EDM, by cyclically loading the plate in four-point bending (tension-to-tension) in a dynamic testing machine. The stress ratio defined as the ratio of minimum to maximum loads was 0.1, where the maximum load used was 120 kN. After introducing the fatigue crack, the specimen was machined and polished to remove the initial notch, thereby leaving the fatigue crack in the plate specimen of final dimension (250 \( \times \) 50 \( \times \) 16) mm. After the potential drop measurements on the fatigue cracked specimen were performed, the specimen containing the crack was heat treated using an electric furnace for clearly observing the fatigue crack. Finally, in order to observe the fatigue crack on the fractured surface, the specimen was broken by subjecting cyclic fatigue loading once again with a stress ratio different from that used for preparing the crack.

The photograph of the CCPPD sensor used for measuring the surface potential drop, and the details of the probe arrangements are shown in Figs. 8(a) and (b), respectively. A constant direct current of 1 A was applied to the specimens through the current input and output probes. Potential drops were measured by the measuring probes within the positions of the current input and output probes. The distance of the current probes and the potential drop measuring probes were 6 and 3 mm, respectively, as shown in Fig. 8(b). The CCPPD sensor is small and easy to deal with, which, in turn, enables us to scan the cracked surface to measure the potential drop as a function of sensor position. The contact of every probe to the specimen surface was kept under constant pressure by using springs. Every probe was made of tungsten so that defacement of the probes was prevented.
with the corresponding FE results [see Fig. 9(b)], and thus of the shallow crack (profile measured across the crack for between the points B and E than that of indicates that the potential drop profiles across the cracks are affected by. The measured results of the change in potential drop, \( V(x, 0) - V_0 \), for the fatigue crack. Here the profile of \( V(\pm 2.5, y) \) is the average of the profiles of \( V(-2.5, y) \) and \( V(2.5, y) \). The variation of \( \xi \) determined from the profiles \( V(0, y) \) and \( V(\pm 2.5, y) \) is also shown in Fig. 11(b). Based on the method of determining the crack length given in Section 3.2, the value of \( 2a \) for the present fatigue crack was estimated as 14.0 mm from Fig. 11(b).

Figure 12 shows the relationship between the potential drop, \( V_1 - V_2 \) and \( b \) obtained by FE analysis. In obtaining the relation, the used value of \( 2a \) was 14.0 mm as evaluated by the preset technique. Moreover, the value of \( w \) was set zero in an attempt to simulate the condition of mating surfaces of the fatigue crack. The value of \( V_1 - V_2 \) obtained from the experiment was 12.1 \( \mu \)V, and the corresponding value of \( b \) of the fatigue crack was evaluated as 0.43 mm from the calibration curve shown in Fig. 12. The photograph of the fractured surface of the fatigue cracked specimen is shown in Fig. 13. The value of \( 2a \) of the tested crack was measured as 13.9 mm. The value of \( 2a \) evaluated by the present technique (14.0 mm) and that measured were judged to be in good

4.3 Experimental results of 3-D fatigue crack

The tested 3-D fatigue crack was very difficult to be identified on the plate surface, and the observation of the crack was realized by the penetrant testing. The tested fatigue crack might be tightly closed.\(^{14}\) It is well-known that crack closure causes a significant problem in NDE of cracks, especially with ultrasonic inspection, and the trials to overcome the crack closure problem are needed for realizing the reliable NDE of cracks.\(^{3,15}\) The photograph of the fatigue crack identified by the penetrant is shown in Fig. 10(a). The potential drop distribution around the fatigue crack obtained by scanning the CCPPD sensor is presented as an image of the cracked surface in Fig. 10(b). Here, the scanning pitch of the sensor was 0.5 mm in both \( x \)- and \( y \)-directions. Figure 10(b) clearly shows the fatigue crack lying in the \( y \)-direction. The measured potential drop profile in the \( x \)-direction at \( y = 0 \) for the fatigue crack is shown in Fig. 11(a). The value of \( V_1 \), i.e., \( V(0, 0) \), was 101.9 \( \mu \)V. And the value of \( V_2 \) was 89.8 \( \mu \)V, which was the average of \( V(-2.5, 0) \) \( [= 90.1 \mu \text{V}] \) and \( V(2.5, 0) \) \( [= 89.5 \mu \text{V}] \). The value of \( V_1 - V_2 \) was thus found to be 12.1 \( \mu \)V. Figure 11(b) shows the measured potential drop profiles in the \( y \)-direction, \( V(0, y) \) and \( V(\pm 2.5, y) \), for the fatigue crack. Here the profile of \( V(\pm 2.5, y) \) is the average of the profiles of \( V(-2.5, y) \) and \( V(2.5, y) \). The reliability and accuracy of the present FE analysis were verified.

4.2 Experimental results of 2-D simulated cracks

The measured results of the change in potential drop, \( V(x, 0) - V_0 \), obtained for the simulated 2-D cracks are compared with the corresponding results of FE analysis in Fig. 9. The comparison for the cracks, \( b = 0.5 \text{ mm} \) and \( b = 2 \text{ mm} \) are shown in Figs. 9(a) and (b), respectively. Here, to investigate the effect of \( w \) on the potential drop profile, the FE analysis was performed for two different conditions of the crack surfaces, i.e., \( w = 0 \) and \( w = 0.1 \text{ mm} \). The FE results of the shallow crack (\( b = 0.5 \text{ mm} \)), as shown in Fig. 9(a), indicate that the potential drop profiles across the cracks are affected by \( w \), and the profile corresponding to \( w = 0.1 \text{ mm} \) shows larger change in the potential drops for the region in between the points B and E than that of \( w = 0 \). On the other hand, the difference between the potential drop profiles of \( w = 0.1 \text{ mm} \) and \( w = 0 \) was found to be negligible for the case of relatively deep crack (\( b = 2 \text{ mm} \)). These results of FE analysis suggest that the width effect should be taken into account for the NDE of shallow cracks. The potential drop profile measured across the crack for \( b = 0.5 \text{ mm} \) and \( w = 0.1 \text{ mm} \) was in good agreement with the FE result of \( w = 0.1 \text{ mm} \) [Fig. 9(a)]. The measured results of the crack, \( b = 2 \text{ mm} \) and \( w = 0.1 \text{ mm} \), were also in good agreement with the corresponding FE results [see Fig. 9(b)], and thus
agreement because the scanning pitch of the experiment was 0.5 mm. The value of \( b \) at the crack center, deepest penetration point, was found to be 0.429 mm on the fractured surface, and thus the value of \( b \) evaluated by the present technique was in very good agreement with the direct measurement.

In the present study, to realize the quantitative NDE of shallow cracks, the sensor used has narrow spacing between the probes, for example, the current probes and the potential drop measuring probes distances were 6 mm and 3 mm, respectively. Wider space of the four-point probes achieves deeper penetration depth of current,\(^5\) and in contrast, the micron-scale four-point probes, which have been recently fabricated,\(^7,8\) focus the current on the surface. The present NDE technique based on the potential drop profiles measured by the four-point probes is applicable for NDE of wide range of cracks, micron-scale to several millimeter, provided that the suitable distances of four-point probes are selected.

As far as the inspection of surface cracks in actual structures is concerned, in addition to the typical vertical cracks, obliquely oriented cracks may also be encountered. However, in most of the cases, the shallow cracks are generally found to be vertical to the surface of a material because the surface containing the crack is basically free from shearing stress and is considered as a plane of principal stress, from where the crack starts to grow in a plane perpendicular to the surface. In some special cases, the cracked surface may not be free from shearing stresses, which would lead to obliquely oriented cracks. The present method of imaging would be equally effective for realizing sensitive detection of the oblique cracks as well as predicting the associated crack length on the surface. The crack depth evaluated by the present method will be equivalent to the projected depth, which would be slightly smaller than the actual depth of the oblique crack depending on the inclination angle.

5. Conclusions

A d-c potential drop technique is proposed for highly sensitive detection as well as accurate quantitative evaluation of both the depth and length of shallow surface cracks. In the present approach, the surface potential drop distributions are measured around the crack by scanning the closely coupled four-point probes sensor. It was found from the results of finite element analysis that the variation of potential drop profiles across and along a crack was very sensitive, especially to the sub-millimeter depth cracks. The superiority of the present technique was verified by conducting the quantitative testing of a 3-D fatigue crack on the surface of a stainless steel plate. The fatigue crack was very difficult to be identified by the visual observation, but the potential drop image obtained by scanning the closely coupled probes sensor on the plate surface clearly showed the fatigue crack. The length and depth of the fatigue crack were evaluated by the present technique as 14.0 and 0.43 mm, respectively, and the associated errors of which were found to be less than 0.8%.

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